M.Tech. Degree Examination, December 2010 Embedded Systems Design

Time: 3 hrs. Max. Marks:100

Note: 1. Answer any FIVE full questions. 2. Standard notations are used.

- 1 a. What are the different processor cores used in the design of embedded systems? What are the considerations in choice of the processor core? (10 Marks)
 - b. What are the different hardware units in a processor based embedded system? Outline their functional utility in system design. (10 Marks)
- 2 a. What are the different modes of serial communication between input/output devices and processor in an embedded system? (10 Marks)
 - b. Explain how 8255 can be used for parallel communication in embedded systems. What are the features of parallel port devices? (10 Marks)
- 3 a. What are the different structural units in a processor? Differentiate between the CISC and RISC processor types and discuss their application. (10 Marks)
 - b. What are the different types of memory devices used in embedded systems? Outline their utility in system design. (10 Marks)
- 4 a. What are the different sources of interrupts n embedded systems? What are the features of interrupt service mechanisms? (10 Marks)
 - b. What are the applications of 1²C and CAN bus for communication between multiple input/output devices? (10 Marks)
- 5 a. Write an assembly level program to turn on and turn off an LED connected to bit-2 of port-A in 16F84 PIC/(or)68HC11 micro-controller. Choose the on-time T_{ON} and the off-time T_{OFF} suitably. (10 Marks)
 - b. Explain the architecture of 16F84/ (or) 68HC11. What are the addressing modes it supports? (10 Marks)
- 6 a. What are the performance features of ADC circuits? Explain the features of ADC systems provided by PIC or Motorolla micro-controllers.

 (10 Marks)
 - b. Explain the features of asynchronous communication provided by PIC or Motorolla microcontrollers. (10 Marks)
- 7 a. What are the petri nets? Illustrate how petri-nets can be used to model event controlled real time program functions. (10 Marks)
 - b. What are the issues in modeling multi-processor systems? Explain the use of synchronous data flow graph models for multi-processor systems. (10 Marks)
- 8 a. Explain the shared data problem. What are the methods used to overcome the problem?
 - b. Explain how message queues and mailboxes can be used for inter-process communication.

 (10 Marks)