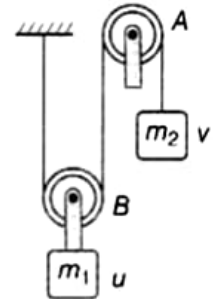


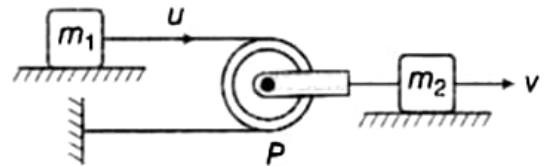
PROBLEMS ON CONSTRAINTS

1. Find the relation between u and v in following cases.

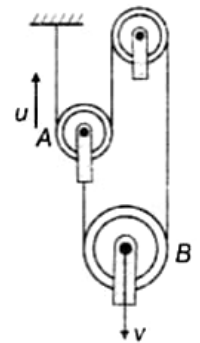
- i. The pulley A is smooth and fixed. The pulley B is free to move. The velocity of block m_1 is u in downward direction and velocity of m_2 is v .



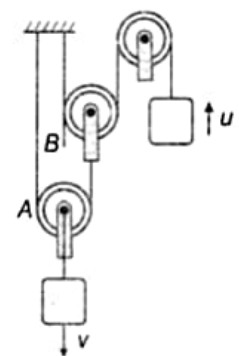
- ii. Movable pulley P is smooth and light.



- iii. Pulley A and B are movable. The velocity of pulley B is v and velocity of A is u .

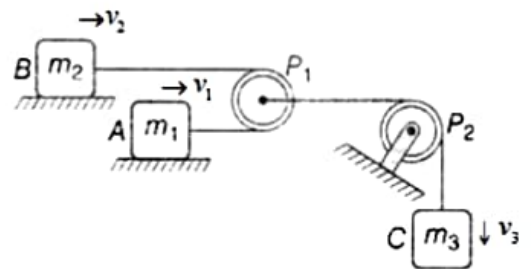


- iv. Pulley A and B are light movable.

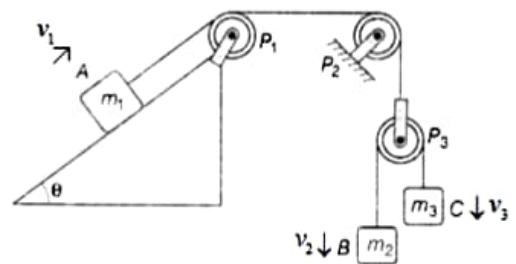


2. Find the relation among v_1, v_2 and v_3 in the following cases.

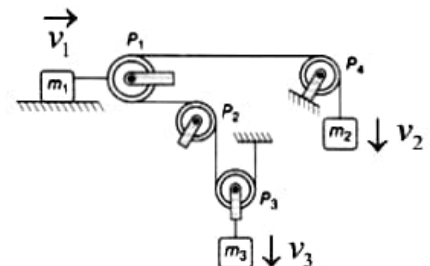
- i. Blocks A and B are placed on the smooth horizontal table. A smooth light pulley P_1 is movable but smooth pulley P_2 is fixed. The velocities of blocks A, B and C are v_1, v_2 and v_3 respectively.



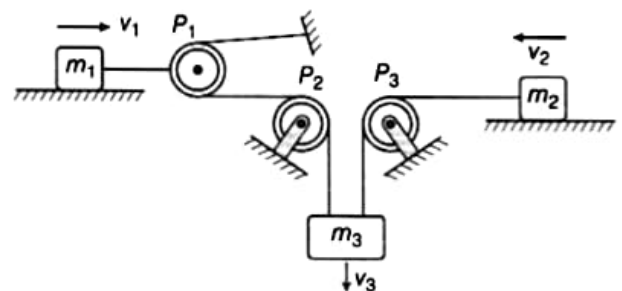
- ii. All ideal pulleys are fixed excepts pulley P_3 . The velocities of A, B and C are v_1, v_2 and v_3 , respectively.



- iii. All ideal pulleys are fixed except pulleys P_1 and P_3 . The velocities of masses m_1, m_2 and m_3 are v_1, v_2 and v_3 , respectively.

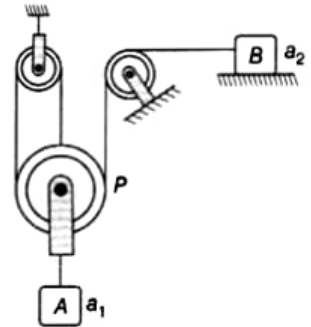


- iv. For the situation shown in figure, blocks are connected through light strings. Light pulley P_1 is movable while other smooth pulleys are fixed.

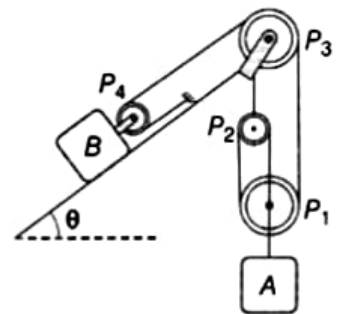


3. Find the relation between a_1 and a_2 in the following cases.

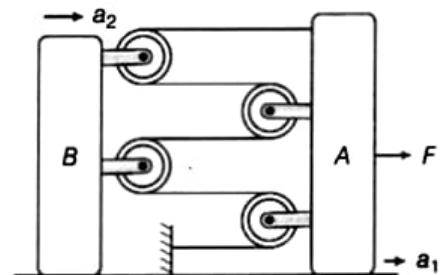
- i. The smooth and light pulley P is movable. The acceleration of blocks A and B are a_1 and a_2 , respectively.



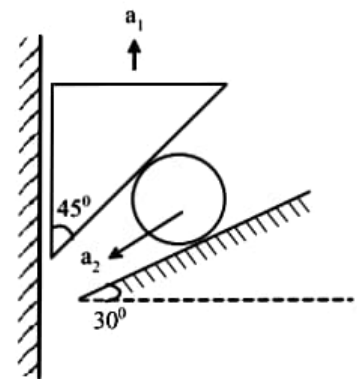
- ii. All pulleys are smooth and light. The pulleys P_2 and P_3 are fixed, but P_1 and P_4 are movable.



- iii. Block A and B are connected through light string passing through light smooth pulleys as shown in figure.



- iv. Find relation between acceleration of triangular block and sphere.



ANSWER KEY

1. **(i)** $v = 2u$, **(ii)** $u = 2v$, **(iii)** $u = 2v$, **(iv)** $u = 4v$
2. **(i)** $v_1 + v_2 = 2v_3$, **(ii)** $v_2 + v_3 = 2v_1$, **(iii)** $2v_1 = v_2 + 2v_3$, **(iv)** $v_2 = v_3 = 2v_1$
3. **(i)** $a_2 = 3a_1$, **(ii)** $3a_1 = 2a_2$, **(iii)** $5a_1 = 4a_2$, **(iv)** $a_1 \sin 45^\circ = a_2 \sin 15^\circ$