```
# Code 01
import RPi.GPIO as GPIO
import time
GPIO.setmode(GPIO.BCM)
LED=[5,6,13,19,26] #GPIOs, where LED is connected
GPIO.setup(LED, GPIO.OUT,initial=0)

while True:
    for i in range(len(LED)):
        GPIO.output(LED[i],GPIO.HIGH)
        time.sleep(.5)
        GPIO.output(LED[i],GPIO.LOW)
        time.sleep(.5)

##########################################################

#Code 02

import RPi.GPIO as GPIO
import time
GPIO.setmode(GPIO.BCM)
pir=23
GPIO.setup(pir, GPIO.IN)

while True:
    if(GPIO.input(pir)):
        print("Motion Detected !")
    else:
        print("Watching...")
    time.sleep(0.5)

##########################################################

# Code 03

import RPi.GPIO as GPIO
import time
GPIO.setmode(GPIO.BCM)
pir=23
led=5
GPIO.setup(pir, GPIO.IN)
GPIO.setup(led, GPIO.OUT)

while True:
    if(GPIO.input(pir)):
        print("Motion Detected !")
        GPIO.output(led,1)
    else:
        print("Watching...")
        GPIO.output(led,0)
    time.sleep(0.5)
```