## Lecture X

Non-homegeneous linear ODE, method of variation of parameters

### 0.1 Method of variation of parameters

Again we concentrate on 2nd order equation but it can be applied to higher order ODE. This has much more applicability than the method of undetermined coefficeints. First, the ODE need not be with constant coefficeints. Second, the nonhomogeneos part $r(x)$ can be a much more general function.

Theorem 1. A particular solution $y_{p}$ to the linear ODE

$$
\begin{equation*}
y^{\prime \prime}+p(x) y^{\prime}+q(x) y=r(x) \tag{1}
\end{equation*}
$$

is given by

$$
\begin{equation*}
y_{p}(x)=-y_{1}(x) \int \frac{y_{2}(x) r(x)}{W\left(y_{1}, y_{2}\right)} d x+y_{2}(x) \int \frac{y_{1}(x) r(x)}{W\left(y_{1}, y_{2}\right)} d x \tag{2}
\end{equation*}
$$

where $y_{1}$ and $y_{2}$ are basis solutions for the homogeneous counterpart

$$
y^{\prime \prime}+p(x) y^{\prime}+q(x) y=0 .
$$

Important note: The (leading) coefficeint of $y^{\prime \prime}$ in (1) must be unity. If it is not unity, then make it unity by dividing the ODE by the leading coefficeint.
Proof: We try for $y_{p}$ of the form

$$
y_{p}(x)=u(x) y_{1}(x)+v(x) y_{2}(x),
$$

where $u(x)$ and $v(x)$ are unknown functins. Now $y_{p}$ should satisfy (1). First, we find $y_{p}^{\prime}(x)=u^{\prime}(x) y_{1}(x)+v^{\prime}(x) y_{2}(x)+u(x) y_{1}^{\prime}(x)+v(x) y_{2}^{\prime}(x)$. Now to make calculations easier (!), we take

$$
\begin{equation*}
u^{\prime}(x) y_{1}(x)+v^{\prime}(x) y_{2}(x)=0 . \tag{3}
\end{equation*}
$$

Next we find $y_{p}^{\prime \prime}(x)=u^{\prime}(x) y_{1}^{\prime}(x)+v^{\prime}(x) y_{2}^{\prime}(x)+u(x) y_{1}^{\prime \prime}(x)+v(x) y_{2}^{\prime \prime}(x)$. Subtituting $y_{p}(x), y_{p}^{\prime}(x)$ and $y_{p}^{\prime \prime}(x)$ into (1) (and using the fact that $y_{1}$ and $y_{2}$ are solution of the homogeneos part), we get

$$
\begin{equation*}
u^{\prime}(x) y_{1}^{\prime}(x)+v^{\prime}(x) y_{2}^{\prime}(x)=r(x) . \tag{4}
\end{equation*}
$$

We solve $u^{\prime}, v^{\prime}$ from (3) and (4) as follows (Cramer's rule):

$$
u^{\prime}=-\frac{r(x) y_{2}(x)}{W\left(y_{1}, y_{2}\right)}, \quad v^{\prime}=\frac{r(x) y_{1}(x)}{W\left(y_{1}, y_{2}\right)}
$$

Integrating we find

$$
u=-\int \frac{y_{2}(x) r(x)}{W\left(y_{1}, y_{2}\right)} d x, \quad v(x)=\int \frac{y_{1}(x) r(x)}{W\left(y_{1}, y_{2}\right)} d x .
$$

Substituting $u$ and $v$ in $y_{p}(x)=y_{1}(x) u(x)+y_{2}(x) v(x)$, we find the required form of $y_{p}$ given in (2).
Note: We don't write constant of integration in the expression of $u$ and $v$, since these can be absorbed with the constants of the genral solution of the homogeneous part.

Example 1. Consider

$$
y^{\prime \prime}-2 y^{\prime}-3 y=x e^{-x}
$$

(This has been solved before by the method of undetermined coefficeints.) The LI solutions of the homogenous part are $y_{1}(x)=e^{-x}$ and $y_{2}(x)=e^{3 x}$. Hence,

$$
y_{p}(x)=y_{1}(x) u(x)+y_{2}(x) v(x)
$$

where

$$
u(x)=-\int \frac{y_{2}(x) r(x)}{W\left(y_{1}, y_{2}\right)} d x, \quad v(x)=\int \frac{y_{1}(x) r(x)}{W\left(y_{1}, y_{2}\right)} d x .
$$

Now $W\left(y_{1}, y_{2}\right)=4 e^{2 x}$. Hence,

$$
\begin{gathered}
u(x)=-\int \frac{x}{4} d x=-\frac{x^{2}}{8} \\
v(x)=\int \frac{x e^{-4 x}}{4} d x=-\frac{x}{16} e^{-4 x}-\frac{1}{64} e^{-4 x}
\end{gathered}
$$

Thus,

$$
y_{p}(x)=-\frac{x^{2}}{8} e^{-x}+e^{3 x}\left(-\frac{x}{16} e^{-4 x}-\frac{1}{64} e^{-4 x}\right)
$$

Hence, the general solution is

$$
y(x)=C_{1} e^{-x}+C_{2} e^{3 x}+y_{p}(x)
$$

Since, the last term of $y_{p}$ can be absorbed with the constant $C_{1}$, we get the same solution as obatined before.

Example 2. Consider

$$
y^{\prime \prime}+y=\tan x
$$

Solution: (This can not be solved by the method of undetermined coefficeint.) The LI solutions of the homogenous part are $y_{1}(x)=\cos x$ and $y_{2}(x)=\sin x$. Hence,

$$
y_{p}(x)=y_{1}(x) u(x)+y_{2}(x) v(x)
$$

where

$$
u(x)=-\int \frac{y_{2}(x) r(x)}{W\left(y_{1}, y_{2}\right)} d x, \quad v(x)=\int \frac{y_{1}(x) r(x)}{W\left(y_{1}, y_{2}\right)} d x
$$

Now $W\left(y_{1}, y_{2}\right)=1$. Hence,

$$
\begin{gathered}
u(x)=-\int \sin x \tan x d x=-\ln |\sec x+\tan x|+\sin x \\
v(x)=\int \sin x d x=-\cos x
\end{gathered}
$$

Thus,

$$
y_{p}(x)=-\cos x \ln |\sec x+\tan x|
$$

Hence, the general solution is

$$
y(x)=C_{1} \cos x+C_{2} \sin x+y_{p}(x)
$$

Example 3. Consider

$$
y^{\prime \prime}+y=|x|, \quad x \in(-1,1)
$$

Solution: You can find the general solution using either the method of undetermined coefficients (tricky!) OR method of variation of parameters. Try yourself.

Example 4. Consider

$$
x y^{\prime \prime}-(1+x) y^{\prime}+y=x^{2} e^{2 x}, \quad x>0
$$

This is linear but the coefficients are not constants. Note that $y_{1}(x)=e^{x}$ is a solution (by inspection!) of

$$
x y^{\prime \prime}-(1+x) y^{\prime}+y=0 .
$$

Let us first divide by the leading coefficient to find

$$
y^{\prime \prime}-\frac{(1+x)}{x} y^{\prime}+\frac{1}{x} y=0
$$

Using reduction of order, we find

$$
y_{2}(x)=y_{1}(x) \int \frac{1}{y_{1}^{2}} e^{\int(1+x) / x d x} d x=(x+1)
$$

The LI solutions of the homogenous part are $y_{1}(x)=e^{x}$ and $y_{2}(x)=(1+x)$.
Divinding by the leading coefficient leads to

$$
y^{\prime \prime}-\frac{(1+x)}{x} y^{\prime}+\frac{1}{x} y=x e^{2 x}
$$

Hence, $r(x)=x e^{2 x}$. Now

$$
y_{p}(x)=y_{1}(x) u(x)+y_{2}(x) v(x)
$$

where

$$
u(x)=-\int \frac{y_{2}(x) r(x)}{W\left(y_{1}, y_{2}\right)} d x, \quad v(x)=\int \frac{y_{1}(x) r(x)}{W\left(y_{1}, y_{2}\right)} d x .
$$

Here $W\left(y_{1}, y_{2}\right)=-x e^{x}$. Hence,

$$
\begin{aligned}
& u(x)=\int(x+1) e^{x} d x=x e^{x} \\
& v(x)=-\int e^{2 x} d x=-\frac{1}{2} e^{2 x}
\end{aligned}
$$

Thus,

$$
y_{p}(x)=\frac{(x-1)}{2} e^{2 x}
$$

Hence, the general solution is

$$
y(x)=C_{1} e^{x}+C_{2}(x+1)+y_{p}(x)
$$

### 0.2 Method of variation of parameters: extension to higher order

We illustrate the method for the third order ODE

$$
\begin{equation*}
y^{\prime \prime \prime}+a(x) y^{\prime \prime}+b(x) y^{\prime}+c(x) y=r(x) . \tag{5}
\end{equation*}
$$

Note that the leading coefficeint is again unity. Suppose the three LI solutions to (5) are $y_{1}, y_{2}$ and $y_{3}$. As before let

$$
\begin{equation*}
y_{p}(x)=u(x) y_{1}(x)+v(x) y_{2}(x)+w(x) y_{3}(x) . \tag{6}
\end{equation*}
$$

We find

$$
y_{p}^{\prime}(x)=u^{\prime}(x) y_{1}(x)+v^{\prime}(x) y_{2}(x)+w^{\prime}(x) y_{3}(x)+u(x) y_{1}^{\prime}(x)+v(x) y_{2}^{\prime}(x)+w(x) y_{3}^{\prime}(x)
$$

As before for the ease of computation (!) we set

$$
\begin{equation*}
u^{\prime}(x) y_{1}(x)+v^{\prime}(x) y_{2}(x)+w^{\prime}(x) y_{3}(x)=0 \tag{7}
\end{equation*}
$$

Now

$$
y_{p}^{\prime \prime}(x)=u^{\prime}(x) y_{1}^{\prime}(x)+v^{\prime}(x) y_{2}^{\prime}(x)+w^{\prime}(x) y_{3}^{\prime}(x)+u(x) y_{1}^{\prime \prime}(x)+v(x) y_{2}^{\prime \prime}(x)+w(x) y_{3}^{\prime \prime}(x)
$$

Again for the ease of computation (!!), we set

$$
\begin{equation*}
u^{\prime}(x) y_{1}^{\prime}(x)+v^{\prime}(x) y_{2}^{\prime}(x)+w^{\prime}(x) y_{3}^{\prime}(x)=0 \tag{8}
\end{equation*}
$$

Further

$$
y_{p}^{\prime \prime \prime}=u^{\prime}(x) y_{1}^{\prime \prime}(x)+v^{\prime}(x) y_{2}^{\prime \prime}(x)+w^{\prime}(x) y_{3}^{\prime \prime}(x)+u(x) y_{1}^{\prime \prime \prime}(x)+v(x) y_{2}^{\prime \prime \prime}(x)+w(x) y_{3}^{\prime \prime \prime}(x)
$$

Subtituting $y_{p}(x), y_{p}^{\prime}(x), y_{p}^{\prime \prime}(x)$ and $y_{p}^{\prime \prime \prime}(x)$ into (5) (and using the fact that $y_{1}, y_{2}$ and $y_{3}$ are solutions of the homogeneos part), we get

$$
\begin{equation*}
u^{\prime}(x) y_{1}^{\prime \prime}(x)+v^{\prime}(x) y_{2}^{\prime \prime}(x)+w^{\prime}(x) y_{3}^{\prime}(x)=r(x) . \tag{9}
\end{equation*}
$$

Now we find $u^{\prime}, v^{\prime}, w^{\prime}$ from (7),(8) and (7) by Cramer's rule. Let

$$
W\left(y_{1}, y_{2}, y_{3}\right)=\left|\begin{array}{ccc}
y_{1} & y_{2} & y_{3} \\
y_{1}^{\prime} & y_{2}^{\prime} & y_{3}^{\prime} \\
y_{1}^{\prime \prime} & y_{2}^{\prime \prime} & y_{3}^{\prime \prime}
\end{array}\right|
$$

be the Wronskian of three LI solutions. (Wronskian can similarly defined for $n$ LI solutions). Then

$$
u^{\prime}=\frac{W_{1}}{W\left(y_{1}, y_{2}, y_{3}\right)}, v^{\prime}=\frac{W_{2}}{W\left(y_{1}, y_{2}, y_{3}\right)} w^{\prime}=\frac{W_{3}}{W\left(y_{1}, y_{2}, y_{3}\right)} .
$$

Here $W_{i}$ is the determinate obtained from $W\left(y_{1}, y_{2}, y_{3}\right)$ by replacing the $i$-th column by the column vector $(0,0, r(x))^{T}$. Hence,

$$
u=\int \frac{W_{1}}{W\left(y_{1}, y_{2}, y_{3}\right)} d x, v=\int \frac{W_{2}}{W\left(y_{1}, y_{2}, y_{3}\right)} d x, w=\int \frac{W_{3}}{W\left(y_{1}, y_{2}, y_{3}\right)} d x
$$

These $u, v, w$ are then substituted into (6) to get $y_{p}$.

