

SOLUTION OF SYSTEM OF LINEAR EQUATIONS

Lecture 1: (a) **Gauss Elimination method (general).**
(b) **Gauss Elimination method (particular case).**

In this section, we shall discuss about the numerical computation of the solution of a system of n linear equations of the form

$$a_{11}^{(1)}x_1 + a_{12}^{(1)}x_2 + \dots + a_{1n}^{(1)}x_n = b_1^{(1)}$$

$$a_{21}^{(1)}x_1 + a_{22}^{(1)}x_2 + \dots + a_{2n}^{(1)}x_n = b_2^{(1)}$$

.....

$$a_{n1}^{(1)}x_1 + a_{n2}^{(1)}x_2 + \dots + a_{nn}^{(1)}x_n = b_n^{(1)}$$

where a_{ij} 's ($i, j=1, 2, \dots, n$) are the coefficients of the unknowns x_1, x_2, \dots, x_n and b_i 's ($i=1, 2, \dots, n$) are constants.

In matrix notation, this can be written in the form

$$A\tilde{x} = \tilde{b}$$

where $A = \begin{pmatrix} a_{11}^{(1)} & a_{12}^{(1)} & \dots & a_{1n}^{(1)} \\ a_{21}^{(1)} & a_{22}^{(1)} & \dots & a_{2n}^{(1)} \\ \dots & \dots & \dots & \dots \\ a_{n1}^{(1)} & a_{n2}^{(1)} & \dots & a_{nn}^{(1)} \end{pmatrix}$ is an $(n \times n)$ matrix, $\tilde{x} = \begin{pmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{pmatrix}$ is a

$(n \times 1)$ matrix of unknowns and $\tilde{b} = \begin{pmatrix} b_1^{(1)} \\ b_2^{(1)} \\ \dots \\ b_n^{(1)} \end{pmatrix}$ is a $(n \times 1)$ matrix of prescribed

constants.

We assume that $\det A \neq 0$, so that the system of n linear equations in n-unknowns has a unique solution. Our aim is to compute n-unknown components x_1, x_2, \dots, x_n , up to desired degree of accuracy.

The methods for solving the system of linear equation can be categorized into two groups:

1. **Direct Method**, (or exact method), where we obtain the solution through a finite number of arithmetic operations, for example, Gauss Elimination method, Crout's method.
2. **Interactive Method**, where a sequence of successive approximations, obtained, which converges to the required solution, up to some desired degree of accuracy, for example, Jacobi's method, Gauss Seidal method.

Gauss-Elimination Method

It is a direct method for finding the solution or the values of unknown of a system of linear equations and is based on the principle of elimination of unknown in successive steps. We first discuss the method considering n -equations and then we shall consider in particular, 3-equations with 3-unknowns.

We consider a system of n -linear equations with n -unknowns as:

$$\left. \begin{aligned}
 a_{11}^{(1)}x_1 + a_{12}^{(1)}x_2 + a_{13}^{(1)}x_3 + a_{14}^{(1)}x_4 + \dots\dots\dots + a_{1,n-1}^{(1)}x_{n-1} + a_{1,n}^{(1)}x_n &= b_1^{(1)} \\
 a_{21}^{(1)}x_1 + a_{22}^{(1)}x_2 + a_{23}^{(1)}x_3 + a_{24}^{(1)}x_4 + \dots\dots\dots + a_{2,n-1}^{(1)}x_{n-1} + a_{2,n}^{(1)}x_n &= b_2^{(1)} \\
 a_{31}^{(1)}x_1 + a_{32}^{(1)}x_2 + a_{33}^{(1)}x_3 + a_{34}^{(1)}x_4 + \dots\dots\dots + a_{3,n-1}^{(1)}x_{n-1} + a_{3,n}^{(1)}x_n &= b_3^{(1)} \\
 \dots\dots\dots \\
 a_{n-1,1}^{(1)}x_1 + a_{n-1,2}^{(1)}x_2 + a_{n-1,3}^{(1)}x_3 + a_{n-1,4}^{(1)}x_4 + \dots\dots\dots + a_{n-1,n-1}^{(1)}x_{n-1} + a_{n-1,n}^{(1)}x_n &= b_{n-1}^{(1)} \\
 a_{n,1}^{(1)}x_1 + a_{n,2}^{(1)}x_2 + a_{n,3}^{(1)}x_3 + a_{n,4}^{(1)}x_4 + \dots\dots\dots + a_{n,n-1}^{(1)}x_{n-1} + a_{n,n}^{(1)}x_n &= b_n^{(1)}
 \end{aligned} \right\} (1)$$

where $a_{ij}^{(1)}$'s ($i, j = 1, 2, 3, \dots, n$) are the coefficient of unknowns and $b_i^{(1)}$'s ($i = 1, 2, 3, \dots, n$) are prescribed constants.

Let $a_{11}^{(1)} \neq 0$. Now multiplying the first equation successively by

$$-\frac{a_{21}^{(1)}}{a_{11}^{(1)}} (= m_{21}), -\frac{a_{31}^{(1)}}{a_{11}^{(1)}} (= m_{31}), -\frac{a_{41}^{(1)}}{a_{11}^{(1)}} (= m_{41}), \dots, \\ -\frac{a_{n-1,1}^{(1)}}{a_{11}^{(1)}} (= m_{n-1,1}), -\frac{a_{n1}^{(1)}}{a_{11}^{(1)}} (= m_{n1})$$

and adding respectively with 2nd, 3rd, 4th, ..., (n-1)th and nth equations of the system we get,

$$\left. \begin{aligned} a_{11}^{(1)}x_1 + a_{12}^{(1)}x_2 + a_{13}^{(1)}x_3 + a_{14}^{(1)}x_4 + \dots + a_{1,n-1}^{(1)}x_{n-1} + a_{1,n}^{(1)}x_n &= b_1^{(1)} \\ a_{22}^{(2)}x_2 + a_{23}^{(2)}x_3 + a_{24}^{(2)}x_4 + \dots + a_{2,n-1}^{(2)}x_{n-1} + a_{2,n}^{(2)}x_n &= b_2^{(2)} \\ a_{32}^{(2)}x_2 + a_{33}^{(2)}x_3 + a_{34}^{(2)}x_4 + \dots + a_{3,n-1}^{(2)}x_{n-1} + a_{3,n}^{(2)}x_n &= b_3^{(2)} \\ \dots & \\ a_{n-1,2}^{(2)}x_2 + a_{n-1,3}^{(2)}x_3 + a_{n-1,4}^{(2)}x_4 + \dots + a_{n-1,n-1}^{(2)}x_{n-1} + a_{n-1,n}^{(2)}x_n &= b_{n-1}^{(2)} \\ a_{n,2}^{(2)}x_2 + a_{n,3}^{(2)}x_3 + a_{n,4}^{(2)}x_4 + \dots + a_{n,n-1}^{(2)}x_{n-1} + a_{n,n}^{(2)}x_n &= b_n^{(2)} \end{aligned} \right\} (2)$$

where

$$a_{22}^{(2)} = a_{22}^{(1)} - \frac{a_{21}^{(1)} \cdot a_{12}^{(1)}}{a_{11}^{(1)}}, a_{23}^{(2)} = a_{23}^{(1)} - \frac{a_{21}^{(1)} \cdot a_{13}^{(1)}}{a_{11}^{(1)}}, \dots ; \\ a_{32}^{(2)} = a_{32}^{(1)} - \frac{a_{31}^{(1)} \cdot a_{12}^{(1)}}{a_{11}^{(1)}}, a_{33}^{(2)} = a_{33}^{(1)} - \frac{a_{31}^{(1)} \cdot a_{13}^{(1)}}{a_{11}^{(1)}}, \dots ; \\ \dots \\ a_{n2}^{(2)} = a_{n2}^{(1)} - \frac{a_{n1}^{(1)} \cdot a_{12}^{(1)}}{a_{11}^{(1)}}, a_{n3}^{(2)} = a_{n3}^{(1)} - \frac{a_{n1}^{(1)} \cdot a_{13}^{(1)}}{a_{11}^{(1)}}, \dots ; \\ b_2^{(2)} = b_2^{(1)} - \frac{b_1^{(1)} \cdot a_{21}^{(1)}}{a_{11}^{(1)}}, b_3^{(2)} = b_3^{(1)} - \frac{b_1^{(1)} \cdot a_{31}^{(1)}}{a_{11}^{(1)}}, \dots .$$

It is clear from the system (2) that except the first equation, the rest (n - 1) equations are free from the unknown x_1 .

Again assuming $a_{22}^{(2)} \neq 0$, multiplying second equation of the system (2)

successively by

$$-\frac{a_{32}^{(2)}}{a_{22}^{(2)}} (= m_{32}), -\frac{a_{42}^{(2)}}{a_{22}^{(2)}} (= m_{42}), \dots, -\frac{a_{n-1,2}^{(2)}}{a_{22}^{(2)}} (= m_{n-1,2}), -\frac{a_{n,2}^{(2)}}{a_{22}^{(2)}} (= m_{n,2}), \dots$$

and adding respectively to 3rd, 4th,, (n-1)th and nth equation of the system (2)

we get,

$$\left. \begin{aligned} a_{11}^{(1)}x_1 + a_{12}^{(1)}x_2 + a_{13}^{(1)}x_3 + a_{14}^{(1)}x_4 + \dots + a_{1,n-1}^{(1)}x_{n-1} + a_{1,n}^{(1)}x_n &= b_1^{(1)} \\ a_{22}^{(2)}x_2 + a_{23}^{(2)}x_3 + a_{24}^{(2)}x_4 + \dots + a_{2,n-1}^{(2)}x_{n-1} + a_{2,n}^{(2)}x_n &= b_2^{(2)} \\ a_{33}^{(3)}x_3 + a_{34}^{(3)}x_4 + \dots + a_{3,n-1}^{(3)}x_{n-1} + a_{3,n}^{(3)}x_n &= b_3^{(3)} \\ a_{43}^{(3)}x_3 + a_{44}^{(3)}x_4 + \dots + a_{4,n-1}^{(3)}x_{n-1} + a_{4,n}^{(3)}x_n &= b_4^{(3)} \\ \dots & \\ a_{n-1,3}^{(3)}x_3 + a_{n-1,4}^{(3)}x_4 + \dots + a_{n-1,n-1}^{(3)}x_{n-1} + a_{n-1,n}^{(3)}x_n &= b_{n-1}^{(3)} \\ a_{n,3}^{(3)}x_3 + a_{n,4}^{(3)}x_4 + \dots + a_{n,n-1}^{(3)}x_{n-1} + a_{n,n}^{(3)}x_n &= b_n^{(3)} \end{aligned} \right\} (3)$$

Here also, we observe that 3rd, 4th up to nth equations of the system (3) are free the unknowns x_1, x_2 .

Repeating the same procedure of elimination of the unknowns, lastly we get a system of equation which is equivalent to the system (1) as:

$$\left. \begin{aligned} a_{11}^{(1)}x_1 + a_{12}^{(1)}x_2 + a_{13}^{(1)}x_3 + a_{14}^{(1)}x_4 + \dots + a_{1,n-1}^{(1)}x_{n-1} + a_{1,n}^{(1)}x_n &= b_1^{(1)} \\ a_{22}^{(2)}x_2 + a_{23}^{(2)}x_3 + a_{24}^{(2)}x_4 + \dots + a_{2,n-1}^{(2)}x_{n-1} + a_{2,n}^{(2)}x_n &= b_2^{(2)} \\ a_{33}^{(3)}x_3 + a_{34}^{(3)}x_4 + \dots + a_{3,n-1}^{(3)}x_{n-1} + a_{3,n}^{(3)}x_n &= b_3^{(3)} \\ a_{44}^{(4)}x_4 + \dots + a_{4,n-1}^{(4)}x_{n-1} + a_{4,n}^{(4)}x_n &= b_4^{(4)} \\ \dots & \\ \dots & \\ a_{n-1,n-1}^{(n-1)}x_{n-1} + a_{n-1,n}^{(n-1)}x_n &= b_{n-1}^{(n-1)} \\ a_{n,n}^{(n)}x_n &= b_n^{(n)} \end{aligned} \right\} (4)$$

The non-zero (by assumption) coefficients $a_{11}^{(1)}, a_{22}^{(2)}, a_{33}^{(3)}, \dots, a_{nn}^{(n)}$ of the system of equations are known as **pivots** and the corresponding equations are known as **pivotal equations**. Please note if any of the coefficients $a_{11}^{(1)}, a_{22}^{(2)}, a_{33}^{(3)}, \dots, a_{nn}^{(n)}$ are zeros, then the system has to be reshuffled so that they are non-zeros.

Now we can get easily calculate the solution of the system of equations (4) as follows: First we find x_n from n th equation, then x_{n-1} from $(n-1)$ th equation after substituting x_n and then successively we shall get all the unknowns $x_1, x_2, x_3, \dots, x_n$ (by the method of back substitution).

Gauss Elimination Method (Particular Case)

In this article we now consider a system of 3-equations with 3-unknowns for better illustration to the readers.

A system of 3-equations with 3-unknowns is given by

$$\left. \begin{aligned} a_{11}^{(1)}x_1 + a_{12}^{(1)}x_2 + a_{13}^{(1)}x_3 &= b_1^{(1)} \\ a_{21}^{(1)}x_1 + a_{22}^{(1)}x_2 + a_{23}^{(1)}x_3 &= b_2^{(1)} \\ a_{31}^{(1)}x_1 + a_{32}^{(1)}x_2 + a_{33}^{(1)}x_3 &= b_3^{(1)} \end{aligned} \right\} \quad (5)$$

where $a_{ij}^{(1)}$'s ($i, j = 1, 2, 3$) and $b_i^{(1)}$'s ($i = 1, 2, 3$) are known constants.

Let $a_{11}^{(1)} \neq 0$. Multiplying the first equation of (5) successively by $-\frac{a_{21}^{(1)}}{a_{11}^{(1)}}$ and $-\frac{a_{31}^{(1)}}{a_{11}^{(1)}}$ adding respectively with 2nd and 3rd equation we get, the system as:

$$\left. \begin{aligned} a_{11}^{(1)}x_1 + a_{12}^{(1)}x_2 + a_{13}^{(1)}x_3 &= b_1^{(1)} \\ a_{22}^{(2)}x_2 + a_{23}^{(2)}x_3 &= b_2^{(2)} \\ a_{32}^{(2)}x_2 + a_{33}^{(2)}x_3 &= b_3^{(2)} \end{aligned} \right\} \quad (6)$$

where

$$a_{22}^{(2)} = a_{22}^{(1)} - \frac{a_{12}^{(1)} \cdot a_{21}^{(1)}}{a_{11}^{(1)}}, \quad a_{23}^{(2)} = a_{23}^{(1)} - \frac{a_{13}^{(1)} \cdot a_{21}^{(1)}}{a_{11}^{(1)}}, \quad b_2^{(2)} = b_2^{(1)} - \frac{b_1^{(1)} \cdot a_{21}^{(1)}}{a_{11}^{(1)}}$$

$$a_{32}^{(2)} = a_{32}^{(1)} - \frac{a_{12}^{(1)} \cdot a_{31}^{(1)}}{a_{11}^{(1)}}, \quad a_{33}^{(2)} = a_{33}^{(1)} - \frac{a_{13}^{(1)} \cdot a_{31}^{(1)}}{a_{11}^{(1)}}, \quad b_3^{(2)} = b_3^{(1)} - \frac{b_1^{(1)} \cdot a_{31}^{(1)}}{a_{11}^{(1)}}$$

Let $a_{22}^{(2)} \neq 0$, Multiplying the second equation by $-\frac{a_{32}^{(2)}}{a_{22}^{(2)}}$ and adding with the 3rd

equation of the system (6) we get,

$$\left. \begin{aligned} a_{11}^{(1)} x_1 + a_{12}^{(1)} x_2 + a_{13}^{(1)} x_3 &= b_1^{(1)} \\ a_{22}^{(2)} x_2 + a_{23}^{(2)} x_3 &= b_2^{(2)} \\ a_{33}^{(3)} x_3 &= b_3^{(3)} \end{aligned} \right\} \quad (7)$$

where $a_{33}^{(3)} = a_{33}^{(2)} - \frac{a_{23}^{(2)} \cdot a_{32}^{(2)}}{a_{22}^{(2)}}$.

The non-zero constants (by assumption) $a_{11}^{(1)}$, $a_{22}^{(2)}$ and $a_{33}^{(3)}$ are called *pivots* and the corresponding equations are called the *pivotal equations*. Now the value of the unknown x_3 can be obtain easily from the third equation, which can be substituted in the second equation to obtain x_2 . Substituting x_3 , x_2 in the first equation x_1 also be determined. Thus, all the unknown are completely known by the method of back substitution.